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# Monte Carlo simulation of the general elliptic operator

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**Abstract.** Several versions of an algorithm for Monte Carlo simulation of solutions of partial differential equations involving a general elliptic operator are developed, with the emphasis on quadratic accuracy and computational efficiency.

## 1. Introduction

Vrbik (1985) describes a quadratically accurate Monte Carlo technique for simulating the action of the operator

$$\exp[-t(-\frac{1}{2}\nabla^2 + \nabla F(\mathbf{r}) + E(\mathbf{r}))] \quad (1)$$

when applied to an arbitrary non-negative function, represented by a random sample of 'configurations'.

Such a simulation can be used to solve

$$-\frac{1}{2}\nabla^2 f(\mathbf{r}, t) + \nabla F(\mathbf{r})f(\mathbf{r}, t) + E(\mathbf{r})f(\mathbf{r}, t) = -(\partial/\partial t)f(\mathbf{r}, t) \quad (2)$$

or its time-independent counterpart posed, usually, as an eigenvalue problem, i.e.

$$-\frac{1}{2}\nabla^2 f(\mathbf{r}) + \nabla F(\mathbf{r})f(\mathbf{r}) + (E(\mathbf{r}) - E_0)f(\mathbf{r}) = 0. \quad (3)$$

We would like to extend these results to the more general

$$\exp[-t(-\frac{1}{2}\nabla_j \nabla_k D_{jk}(\mathbf{r}) + \nabla F(\mathbf{r}) + E(\mathbf{r}))] \quad (4)$$

(with implied summation over each pair of identical indices), where  $D(\mathbf{r})$  is a symmetric positive-definite matrix for all values of  $\mathbf{r}$  ( $N$ -dimensional vector). Also note that  $D_{jk}(\mathbf{r})$  is inside the operational range of both  $\nabla_j$  and  $\nabla_k$ .

This extension will be useful for solving all physical problems described by the Fokker-Planck equation and having a non-negative solution. The most eminent examples are the phenomenon of diffusion (possibly accompanied by creation/absorption of particles), heat conduction and flow of fluids through porous media, allowing a non-homogeneous environment undergoing its own motion.

Another potential application relates to solving the Schrödinger equation to obtain the ground state of a complex system of particles (atoms or molecules). One may seek a solution in the form of  $f(\mathbf{R})g(\mathbf{R})$ , where  $f(\mathbf{R})$  is a known function of the particles' locations, constructed to approximate the cusps of the exact solution. This should smooth out the 'rough edges' of the remaining  $g(\mathbf{R})$  function to be simulated (more accurately) by the proposed technique. Thus  $f(\mathbf{R})$  will effectively become the new

(varying) diffusion coefficient and will similarly modify the other terms of the original equation.

**2. Linearly accurate solution**

In this section we aim to achieve first-order accuracy (in terms of expanding expression (4) in  $t$ ), which means that the error of the corresponding procedure for solving (3) will be proportional to  $t$  (the discrete time step of the simulation).

We already know how to simulate operators corresponding to the second and third terms of (4) (see Reynolds *et al* (1982) or Vrbik and Rothstein (1985)) via ‘drift’ and ‘branching’, respectively, so the only missing component remains the simulation of the ‘diffusion’ operator

$$\exp(\frac{1}{2}t \nabla_j \nabla_k D_{jk}(\mathbf{r})). \tag{5}$$

We claim that this can be achieved by the following.

- (i) Finding a matrix  $\mathbf{D}^{1/2}(\mathbf{r})$  such that

$$\mathbf{D}^{1/2} \cdot (\mathbf{D}^{1/2})^T = \mathbf{D}(\mathbf{r}). \tag{6}$$

Note that this can be done easily by choosing  $\mathbf{D}^{1/2}$  to have the lower-triangular form (and *not* the standard symmetric solution obtained by diagonalising  $\mathbf{D}$ ).

- (ii) Advancing each configuration  $\mathbf{r}$  to a new location  $\mathbf{r}'$  (see Vrbik 1985) by

$$\mathbf{r}' = \mathbf{r} + \mathbf{D}^{1/2}(\mathbf{r}) \cdot \mathbf{z} \tag{7}$$

where the  $z_i$  are  $N$  independent random values drawn from a symmetric (such as normal or uniform) distribution with zero mean and variance equal to  $t$ .

To prove (7), first consider the following function of  $\mathbf{r}'$ ,  $\mathbf{r}$  and  $t$ :

$$G(\mathbf{r}' \leftarrow \mathbf{r}, t) = (2\pi t)^{-N/2} \det(\mathbf{D}^{-1/2}(\mathbf{r})) \exp[-(\mathbf{r}' - \mathbf{r})^T \cdot \mathbf{D}^{-1}(\mathbf{r}) \cdot (\mathbf{r}' - \mathbf{r})/2t] \tag{8}$$

where  $\mathbf{D}^{-1/2} = (\mathbf{D}^{1/2})^{-1}$ . Note that

$$\int G(\mathbf{r}' \leftarrow \mathbf{r}, t) f(\mathbf{r}) d\mathbf{r} \tag{9}$$

is, in statistical terms, equivalent to (7), with  $f(\mathbf{r})$  being the probability density function of  $\mathbf{r}$ , and  $\mathbf{z}$  having the normal distribution mentioned above.

If we now define

$$B_{ij} = D_{ij}^{-1/2}(\mathbf{r}) + [\nabla_j D_{ik}^{-1/2}](\mathbf{r} - \mathbf{r}')_k \tag{10}$$

(the operational range of  $\nabla$  being restricted to the square brackets), the substitution

$$\mathbf{z} = \mathbf{D}^{-1/2} \cdot (\mathbf{r} - \mathbf{r}') \tag{11}$$

(thus  $\partial z_i / \partial r_j = B_{ij}$ ) enables us to write

$$\lim_{t \rightarrow 0} \int G(\mathbf{r}' \leftarrow \mathbf{r}, t) \cdot f(\mathbf{r}) d\mathbf{r} = \lim_{t \rightarrow 0} \int (2\pi t)^{-N/2} \times \exp(-\mathbf{z}^2/2t) \det(\mathbf{D}^{-1/2})/\det(\mathbf{B}) \cdot f(\mathbf{r}(\mathbf{z})) dz = f(\mathbf{r}') \tag{12}$$

since

$$\lim_{t \rightarrow 0} (2\pi t)^{-N/2} \exp(-z^2/2t) = \delta(z)$$

$$\delta(z) dz = \delta(\mathbf{r} - \mathbf{r}') d\mathbf{r} \quad \text{and} \quad \det(\mathbf{D}^{-1/2})/\det(\mathbf{B})|_{\mathbf{r}=\mathbf{r}'} = 1. \tag{13}$$

Thus the zeroth-order term of (9) (seen as an operator applied to  $f$ ) is the identity. To derive its first-order terms, we need

$$-\lim_{t \rightarrow 0} \frac{\partial}{\partial t} \int G(\mathbf{r}' \leftarrow \mathbf{r}, t) f(\mathbf{r}) d\mathbf{r}$$

$$= -\lim_{t \rightarrow 0} \frac{1}{2} \int (2\pi t)^{-N/2} [\nabla_z^2 \exp(-z^2/2t)] \cdot \det(\mathbf{D}^{-1/2})/\det(\mathbf{B}) f(\mathbf{r}(z)) dz$$

$$= -\lim_{t \rightarrow 0} \frac{1}{2} \int (2\pi t)^{-N/2} \exp(-z^2/2t) \cdot \nabla_z^2 \det(\mathbf{D}^{-1/2})/\det(\mathbf{B}) f(\mathbf{r}(z)) dz$$

$$= -\frac{1}{2} \int \delta(\mathbf{r} - \mathbf{r}') B_{ji}^{-1} \nabla_j B_{ki}^{-1} \nabla_k \det(\mathbf{D}^{-1/2})/\det(\mathbf{B}) f(\mathbf{r}) d\mathbf{r} \tag{14}$$

as  $\nabla_{zi} = B_{ji}^{-1} \nabla_j$ .

Explicit evaluation of the last integral is rather tedious and rests on the following formulae:

$$\nabla_j B_{ki}^{-1}|_{\mathbf{r}=\mathbf{r}'} = (A_{jil} + A_{lij}) D_{ik}^{1/2}(\mathbf{r}')$$

$$\nabla_k \det(\mathbf{D}^{-1/2})/\det(\mathbf{B})|_{\mathbf{r}=\mathbf{r}'} = C_k(\mathbf{r}') \tag{15}$$

and

$$\nabla_j \nabla_k \det(\mathbf{D}^{-1/2})/\det(\mathbf{B}) = C_k C_j + \nabla_k C_j + \nabla_j C_k + A_{muk} A_{umj} \tag{16}$$

where  $C_k = [\nabla_m D_{mu}^{1/2}] D_{ui}^{-1/2}$  and  $A_{jil} = [\nabla_j D_{iu}^{1/2}] D_{ul}^{-1/2}$ .

When confirming these, remember that, in general,

$$\nabla H_{ki}^{-1} = -H_{ki}^{-1} [\nabla H_{lm}] H_{mi}^{-1} \quad \nabla \det\{\mathbf{H}\} = [\nabla H_{jk}] H_{kj}^{-1} \det\{\mathbf{H}\}.$$

With the help of these, one obtains as the final result of integration (14)

$$-\frac{1}{2} \nabla_j \nabla_k D_{jk} f(\mathbf{r}') \tag{17}$$

as desired.

### 3. Quadratically accurate solution

To derive a  $t^2$  accurate analogue of (8), it is necessary to use the more powerful technique of Risken (1984) which utilises the Fourier transform of the  $\delta$  function. This yields

$$G(\mathbf{r}' \leftarrow \mathbf{r}, t) = \exp[-t(-\frac{1}{2} \nabla_i \nabla_j D_{ij}(\mathbf{r}))^\wedge] \delta(\mathbf{r} - \mathbf{r}')$$

$$= \exp[(t/2) D_{ij} \nabla_i \nabla_j] (2\pi)^{-N} \int \exp\{i\mathbf{u}(\mathbf{r} - \mathbf{r}')\} d\mathbf{u}$$

$$\begin{aligned}
&= (2\pi)^{-N} \int [1 - (t/2)D_{ij}u_i u_j + (t^2/8)D_{kl}u_k u_l D_{ij}u_i u_j \\
&\quad - (t^2/8)D_{kl}[\nabla_k \nabla_l D_{ij}]u_i u_j \\
&\quad - i(t^2/4)D_{kl}[\nabla_l D_{ij}]u_i u_j u_k + \dots] \exp[iu(\mathbf{r} - \mathbf{r}')] d\mathbf{u} \quad (18)
\end{aligned}$$

where the dots imply terms of third and higher order in  $t$ ,  $i^2 = -1$ , and the superscript  $\mathbf{A}$  turns an operator into its adjoint ( $-\frac{1}{2}D_{ij}\nabla_i\nabla_j$  in this case).  $\mathbf{D}$  and its derivatives are to be evaluated at  $\mathbf{r}$  ( $\mathbf{r}'$  is considered a fixed parameter here).

The last integral can be easily carried out (to within the  $t^2$  accuracy), resulting in the probability density function of the random variable  $\mathbf{r}' - \mathbf{r}$  (now,  $\mathbf{r}'$  is considered varying and  $\mathbf{r}$  fixed!). Unfortunately, this itself would not provide an explicit prescription for simulating values from such a distribution; thus we have to employ the following alternative approach.

From the definition of a characteristic function of a distribution and the related theory (see, for example, Cramer 1971), it is immediately obvious that the following expression from the last integral

$$\begin{aligned}
&1 - (t/2)D_{ij}u_i u_j + (t^2/8)D_{kl}u_k u_l D_{ij}u_i u_j - (t^2/8)D_{kl}[\nabla_k \nabla_l D_{ij}]u_i u_j \\
&\quad - i(t^2/4)D_{kl}[\nabla_l D_{ij}]u_i u_j u_k + \dots \quad (19)
\end{aligned}$$

represents the characteristic function of the required distribution. From this, we can determine all the distribution's moments. These are

$$\begin{aligned}
M_i^{(1)} &= 0 + \dots \\
M_{ij}^{(2)} &= tD_{ij} + (t^2/4)D_{kl}[\nabla_k \nabla_l D_{ij}] + \dots \\
M_{ijk}^{(3)} &= (t^2/2)(D_{kl}[\nabla_l D_{ij}] + D_{il}[\nabla_l D_{kj}] + D_{jk}[\nabla_l D_{ik}]) + \dots \\
M_{ijkl}^{(4)} &= t^2(D_{ij}D_{kl} + D_{ik}D_{jl} + D_{il}D_{jk}) + \dots
\end{aligned} \quad (20)$$

for  $i, j, k, l = 1, 2, \dots, N$ , all the higher moments being zero (in the  $+\dots$  sense). Note that the moments have been properly symmetrised.

All we have to do now is to construct a random vector with these moments and use it for the actual simulation of  $\mathbf{r}' - \mathbf{r}$ . It is not difficult to check that a possible solution is

$$D_{ij}^{1/2}z_j + (t/8)D_{jm}^{-1/2}D_{kl}[\nabla_k \nabla_l D_{mi}]z_j + R_{ijk}z_j z_k - tR_{ijj} + tS_{ij}z_j \quad (21)$$

where

$$\begin{aligned}
R_{ijk} &= \frac{1}{4}D_{jm}^{-1/2}[\nabla_l D_{mi}]D_{lk}^{1/2} \\
S_{ij} &= -\frac{1}{2}D_{jm}^{-1/2}(R_{mlk}R_{ilk} + R_{mlk}R_{ikl})
\end{aligned}$$

and  $\mathbf{z}$  is a random vector with independent components generated from the normal distribution with zero mean and variance equal to  $t$  (or an equivalent—any symmetric distribution with the same first four moments will do; let us call such a distribution  $\mathbf{N}\{0, t\}$ ).

The essential formulae to help verify (21) are

$$\begin{aligned}
\mathbb{E}(z_i) &= 0 \\
\mathbb{E}(z_i z_j) &= \delta_{ij}t \\
\mathbb{E}(z_i z_j z_k) &= 0
\end{aligned} \quad (22)$$

and

$$\mathbb{E}(z_i z_j z_k z_l) = (\delta_{ij}\delta_{kl} + \delta_{ik}\delta_{jl} + \delta_{il}\delta_{jk})t^2$$

where  $\mathbb{E}$  denotes the expected value of a random variable.

Note that in the isotropic case of  $D_{ij}(\mathbf{r}) = \delta_{ij}D(\mathbf{r})$ , expression (21) reduces to

$$D^{1/2}z_i + (t/8)D^{1/2}[\nabla^2 D]z_i + (1/4)[\nabla_j D]z_j - (t/4)[\nabla_i D]z_i - (t/32)D^{-1/2}([\nabla_j D][\nabla_j D]z_i + [\nabla_i D][\nabla_j D]z_j). \tag{23}$$

The actual simulation (of both the general and isotropic case) can be simplified even further (with the objective of avoiding derivatives of  $D_{ij}$ ) if we replace, in expression (21),

$$tD_{kl}[\nabla_k \nabla_l D_{mi}] \quad \text{by} \quad (D^{(+)} + D^{(-)} - 2D(\mathbf{r}))_{mi} \tag{24}$$

and

$$R_{ijk} \quad \text{by} \quad (1/8t)D_{jm}^{-1/2}(D^{(+)} - D^{(-)})_{mi}x_k$$

where  $\mathbf{x}$  is a random vector generated, *independently of*  $\mathbf{z}$ , from  $N\{0, t\}$  and

$$D^{(+)} = D(\mathbf{r} + D^{1/2}(\mathbf{r}) \cdot \mathbf{x}) \tag{25}$$

$$D^{(-)} = D(\mathbf{r} - D^{1/2}(\mathbf{r}) \cdot \mathbf{x}).$$

It is a simple exercise to check that such a replacement will not change the moments of (21); thus the final version of simulating 'diffusion' of a configuration with an initial location at  $\mathbf{r}$  is to advance it by adding, to  $\mathbf{r}$ , the following random vector:

$$D_{ij}^{1/2}z_j + (1/8)(D^{(+)} + D^{(-)} - 2D)_{ij}Z_j + (1/8t)z_k x_k (D^{(+)} - D^{(-)})_{ij}Z_j - (1/8)(D^{(+)} - D^{(-)})_{ij}X_j - (1/128t)x_k x_k (D^{(+)} - D^{(-)})_{ij}D_{jl}^{-1}(D^{(+)} - D^{(-)})_{lm}Z_m - (1/128t)(D^{(+)} - D^{(-)})_{ij}X_j \cdot X_l (D^{(+)} - D^{(-)})_{lm}Z_m \tag{26}$$

where  $\mathbf{z}$  and  $\mathbf{x}$  are generated, independently, from  $N\{0, t\}$  and

$$Z_j = z_j D_{ij}^{-1/2} \quad \text{and} \quad X_j = x_j D_{ij}^{-1/2}.$$

Computationally, this will involve three evaluations of  $D$ , one matrix inversion and some further simple matrix manipulation (note that the full matrix multiplication is *not* required). This seems a relatively modest cost of a potentially significant increase in accuracy.

### References

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